Generalized Inverses and Applications

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We will present results on matrix generalized inverses with some applications. It is well-known that a square complex matrix A is invertible if and only if $det(A) \neq 0$. In this case $AA^{-1} = A^{-1}A = I$, where I is the identity matrix of the appropriate dimension. However, in many situations the considerd matrix is not invertible, or not square.

There are several ways to define a generalized inverse of a general complex matrix. If the matrix $A \in \mathbb{C}^{m \times n}$ is given, then the Moore-Penrose of A is the matrix $A^{\dagger} \in \mathbb{C}^{n \times m}$ satisfying the conditions

(1)
$$AA^{\dagger}A = A$$
, (2) $A^{\dagger}AA^{\dagger} = A^{\dagger}$, (3) $(AA^{\dagger})^* = AA^{\dagger}$, (4) $(A^{\dagger}A)^* = A^{\dagger}A$.

The Moore-Penrose inverse of a complex matrix always exists and it is unique. If A is square and invertible, then $A^{\dagger} = A^{-1}$, i.e. in this case the ordinary and the Moore-Penrose inverse of A coincide.

Furthermore, if a vector $b \in \mathbb{C}^n$ is also given, we want to solve the equation Ax = b. In the most general situation, the obvious candidate for a solution is $x = A^{\dagger}b$. Such x minimizes the norm ||Ax - b|| and such x has the minimum norm ||x|| among all other minimizers. This is the approximation property of the Moore-Penrose inverse. The Moore-Penrose inverse is also connected with the Singular value decomposition of a complex matrix and linear regresion.

Now, is $S \subset \{1, 2, 3, 4\}$, we can define a generalized inverse $A^{(S)}$ of A, such that only equations from S are satisfied. Thus, we obtain the following classes of generalized inverses: $\{1\}$ -inverses, $\{2\}$ -inverses, $\{1, 2\}$ -inverses, etc. This clases are also important in many applications.

If we consider a square matrix $A \in \mathbb{C}^{m \times m}$, then the commutativity conditions can be involved. For previously given A, the Drazin inverse $A^D \in \mathbb{C}^{m \times m}$ satisfy the conditions

(2)
$$A^D A A^D = A^D$$
, (5) $A A^D = A^D A$, $A^{n+1} A^D = A^n$

for some $n \in \mathbb{N}_0$. The least such n is called the Drazin index of A, denoted by $\operatorname{ind}(A)$. The Drazin inverse A^D of $A \in \mathbb{C}^{m \times m}$ is unique and always exists. We have $\operatorname{ind}(A) = 0$ if and only if A is invertible, and in this case $A^D = A^{-1}$. If $\operatorname{ind}(A) \leq 1$, then the multiplicative semigroup generated by $\{A, A^D\}$ is actually a group with the unit AA^D . For this special reason, if $\operatorname{ind}(A) \leq 1$, then $A^D = A^{\#}$ is the group inverse of A. Thus, the group inverse of A, $\operatorname{ind}(A) \leq 1$, is the unique matrix $A^{\#}$ satisfying

(1)
$$AA^{\#}A = A$$
, (2) $A^{D}AA^{D} = A^{D}$, (5) $AA^{D} = A^{D}A$.

If J is the Jordan normal form of $A \in \mathbb{C}^{m \times n}$, and J(0) is the appropriate Jordan block corresponding to the eigenvalue $\{0\}$ (if J(0) exists), then $\operatorname{ind}(A)$ is the index of nilpotencity of J(0). Of course, J(0) does not exists if and only if $\operatorname{ind}(A) = 0$.

Drazin inverse have applications in finite Markov chains and signular systems of differential equations.

Lectures will be given accorging to the references and with the following containts.

Lecture 1. Moore-Penrose inverse, $\{1\}$ -, $\{2\}$ - and $\{1, 2\}$ -generalized inverses and related topics.

Lecture 2. Drazin inverse and group inverse.

Lecture 3. Computation of generalized inverses and solving matrix equations.

Lecture 4 and Lecture 5. Applications of generalized inverses: parallel sums and shorted matrices, linear regression, finite Markov chains, singular systems of differential equations.

References

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